

# IE605: Engineering Statistics

## Lecture 11

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## Previous Lecture:

- ▶ Data Reduction
- ▶ Sufficiency principle
- ▶ Sufficient Statistics
- ▶ Factorization theorem
- ▶ Minimum statistics
- ▶ Ancillary statistics

## This Lecture:

- ▶ Likelihood functions

## Likelihood function

Given that  $\mathbf{X} = \mathbf{x}$  is observed, the function  $\theta$  defined by

$$L(\theta|\mathbf{x}) = \begin{cases} f(\mathbf{x}|\theta) & \text{if } \mathbf{X} \text{ is continuous} \\ P_{\theta}(\mathbf{X} = \mathbf{x}) & \text{if } \mathbf{X} \text{ is discrete} \end{cases}$$

When a sample  $\mathbf{x}$  is observed. For a given parameters  $(\theta_1, \theta_2)$  if

$$P_{\theta_1}(\mathbf{X} = \mathbf{x}) = L(\theta_1|\mathbf{x}) > L(\theta_2|\mathbf{x}) = P_{\theta}(\mathbf{X} = \mathbf{x})$$

Sample would have come more likely from parameter  $\theta_1$  than  $\theta_2$ .  
 $\theta_1$  is more **plausible** value of true parameter  $\theta$  than  $\theta_2$

## Examples

- ▶ **Binomial:** Suppose  $X$  is Binomial with known  $n$  and unknown  $p$ . If  $X = x$  is observed, then the likelihood function is

$$L(p|x) = P_p(X = x) = \binom{n}{x} p^x (1 - p)^{n-x}.$$

- ▶ **Exponential:** if  $\mathbf{X} = (X_1, X_2, \dots, X_n)$ , where  $X_i$ s are iid exponential with unknown  $\lambda$

$$L(\lambda|x) = f(x|\lambda) = \prod_{i=1}^n \lambda \exp\{-\lambda x_i\}$$

- ▶ **Gaussian:** if  $\mathbf{X} = (X_1, X_2, \dots, X_n)$ , where  $X_i$ s are iid Gaussian with unknown  $\mu$  and known  $\sigma^2$

$$L(\mu|x) = f(x|\mu) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\{-(x_i - \mu)^2/2\sigma^2\}$$

## Likelihood Principle

If samples  $\mathbf{x}$  and  $\mathbf{y}$  are such that  $L(\theta|\mathbf{x}) = C(\mathbf{x}, \mathbf{y})L(\theta|\mathbf{y})$  for all  $\theta$ , then conclusion drawn from  $\mathbf{x}$  and  $\mathbf{y}$  are identical.  $C(\mathbf{x}, \mathbf{y})$  is independent of  $\theta$ .

**Example:** Let  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  are iid Gaussian with unknown  $\mu$  and known  $\sigma^2$ . For any samples  $\mathbf{x}$  and  $\mathbf{y}$

$$L(\mu|\mathbf{x}) = f(\mathbf{x}|\mu) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\{-(x_i - \mu)^2/2\sigma^2\}$$

$$L(\mu|\mathbf{y}) = f(\mathbf{y}|\mu) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\{-(y_i - \mu)^2/2\sigma^2\}$$

$$C(\mathbf{x}, \mathbf{y}) = \exp\left\{-\sum_{i=1}^n (x_i - \bar{x})/2\sigma^2 + \sum_{i=1}^n (y_i - \bar{y})/2\sigma^2\right\}$$

$L(\mu|\mathbf{x}) = L(\mu|\mathbf{y})$  if and only if  $\bar{x} = \bar{y}$ . Same conclusion is drawn about  $\mu$  from two samples  $\mathbf{x}$  and  $\mathbf{y}$  satisfying  $\bar{x} = \bar{y}$

## Maximum Likelihood Estimators

For a given  $\mathbf{x}$ , let  $\hat{\theta}(\mathbf{x})$  be the parameter at which  $L(\theta|\mathbf{x})$  attains maximum value as a function of  $\theta$ , i.e.,

$$\hat{\theta}(\mathbf{x}) \in \arg \max_{\theta} L(\theta|\mathbf{x})$$

$\hat{\theta}(\mathbf{x})$  is the Maximum Likelihood Estimator (MLE) of parameter  $\theta$  at  $\mathbf{X} = \mathbf{x}$ .

- ▶ MLE is the **parameter point** for which the observed point is most likely
- ▶ In general, MLE is a good **point estimator** and is by far the most popular technique for deriving estimators.

# Solving MLE

- ▶ How to find global optima?
- ▶ How to verify the found solution is the global optima?
- ▶ When  $L(\boldsymbol{\theta}|\mathbf{x})$  is differentiable in each component  $\theta_i$ , simple differential calculus can be applied.

$$\frac{\partial}{\partial \theta_i} L(\boldsymbol{\theta}|\mathbf{x}) = 0, \quad i = 1, 2, \dots, k.$$

- ▶ How sensitive is the solution to small changes in sample data

## Examples:

**Normal Likelihood:**  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  be i.i.d.  $\sim \mathcal{N}(\theta, 1)$ .

- ▶ Likelihood function is

$$L(\theta|\mathbf{x}) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} \exp \left\{ -\frac{(x_i - \theta)^2}{2} \right\}$$

- ▶  $\frac{d}{d\theta} L(\theta|\mathbf{x}) = 0 \implies \sum_{i=1}^n (x_i - \theta) = 0$ . (first order condition)
- ▶  $\hat{\theta}(\mathbf{x}) = \frac{\sum_{i=1}^n x_i}{n} = \bar{x}$ . Is  $\bar{x}$  global optimal?
- ▶ Check  $\frac{d^2}{d\theta^2} L(\theta|\mathbf{x})|_{\theta=\bar{x}} < 0$ ? (second order condition)

**Bernoulli Likelihood:**  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  be i.i.d.  $\sim \text{Ber}(p)$ .

- ▶ Likelihood function is

$$L(p|\mathbf{x}) = \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i} = p^{\sum_{i=1}^n x_i} (1-p)^{n - \sum_{i=1}^n x_i}$$

- ▶ Solve  $\frac{d}{dp} L(p|\mathbf{x}) = 0$  and find  $\bar{p}$  (first order condition)
- ▶ Check  $\frac{d^2}{dp^2} L(p|\mathbf{x})|_{p=\bar{p}} < 0$  (second order condition)



## Log Likelihood Functions

- ▶ It is easier work with logarithms of Likelihood functions
- ▶  $\log L(\boldsymbol{\theta}|\mathbf{x})$  instead of  $L(\boldsymbol{\theta}|\mathbf{x})$ , called log likelihood function
- ▶ As  $\log(\cdot)$  is monotone, solution of maximization problem does not change!
- ▶ Normal Log Likelihood:

$$\log L(\theta|\mathbf{x}) = n \log \frac{1}{\sqrt{2\pi}} - \frac{\sum_{i=1}^n (x_i - \theta)^2}{2}$$

- ▶ Binomial Log Likelihood:

$$\log L(p|\mathbf{x}) = \left( \sum_{i=1}^n x_i \right) \log p + \left( n - \sum_{i=1}^n x_i \right) \log(1 - p)$$

$$\frac{d}{dp} L(p|\mathbf{x}) = 0 \implies \hat{p} = \bar{x}$$

## Other Point Estimators:

- ▶ Maximum Likelihood estimator
- ▶ Method of moments
- ▶ Bayes method
- ▶ Expectation Maximization (EM) method

## Method of Moments (MM)

- ▶ Method of Moments(MM) is one the oldest method for finding point estimator (since 1800!)
- ▶ MM estimators are found by equating the first  $k$  sample moments to the corresponding population moments
- ▶  $\mathbf{X}$  be a sample from pmf/pdf  $f(\mathbf{x}|(\theta_1, \theta_2, \dots, \theta_k))$

$$m_1 = \frac{1}{n} \sum_{i=1}^n X_i^1, \quad \mu'_1 = \mathbb{E}(X^1)$$

$$m_2 = \frac{1}{n} \sum_{i=1}^n X_i^2, \quad \mu'_2 = \mathbb{E}(X^2)$$

⋮

$$m_k = \frac{1}{n} \sum_{i=1}^n X_i^k, \quad \mu'_k = \mathbb{E}(X^k)$$

Usually,  $\mu'_j$ 's will be function of  $(\theta_1, \theta_2, \dots, \theta_k)$ , say

$$\mu'_j(\theta_1, \theta_2, \dots, \theta_k)$$

## Solving MMs

- ▶ Obtain  $k$  equations by equating

$$m_1 = \mu'_1(\theta_1, \theta_2, \dots, \theta_k)$$

$$m_2 = \mu'_2(\theta_1, \theta_2, \dots, \theta_k)$$

⋮

$$m_k = \mu'_k(\theta_1, \theta_2, \dots, \theta_k)$$

**Normal Method of Moments:**  $X = (X_1, X_2, \dots, X_n)$  are i.i.d.  $\mathcal{N}(\mu, \sigma^2)$ .  $\theta = (\theta_1, \theta_2) = (\mu, \sigma^2)$ .

- ▶  $m_1 = \frac{1}{n} \sum_{i=1}^n X_i = \bar{X}$  (first moment),  $m_2 = \frac{1}{n} \sum_{i=1}^n X_i^2$  (second moment)
- ▶  $\mu'_1(\theta_1, \theta_2) = \mu$  (mean),  $\mu'_2(\theta_1, \theta_2) = \mu^2 + \sigma^2$  (second moment).
- ▶

$$\frac{\sum_{i=1}^n X_i}{n} = \theta_1 \quad \text{and} \quad \frac{\sum_{i=1}^n X_i^2}{n} = \theta_1^2 + \theta_2.$$